Dependence of spicule properties on magnetic field – results from Magnetohydrodynamics simulations

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ABSTRACT

Solar spicules are plasma jets observed in the interface region between the visible solar surface and the corona. At any given time, there are millions of spicules present all over the Sun. While various models attempt to elucidate their origin and characteristics, here, we consider the one driven by the magneto-convection undulations. The radiative magneto-hydrodynamical (rMHD) equations are solved using PENCIL CODE with a spatial resolution of 16 km using various magnetic field strengths. The obtained rMHD simulation data are investigated to unveil the various trends in spicular properties as function of the applied magnetic fields. The important outcome of this study is the finding of a consistent reduction in both the number density and the maximum height reached by spicules as magnetic field strength increases. We also use parabolic fitting on time-distance curves of spicules that are taller than 75th percentile in the distribution, in order to find a relation between deceleration of the spicule tip and the magnetic field strength. Our results offer insights into the response of solar spicules to magnetic field strength.

Keywords: Solar spicules – MHD – Magnetic fields

1. INTRODUCTION

Spicules, first discovered by Secchi (1877) and later named spicules by Roberts (1945), are elongated plasma jets (4000-20,000 km in height), a forest of which is observed all over the chromosphere (Zhang et al. 2012; Beckers 1972; Sterling 2000; Tsiropoula et al. 2012). Spicules and macrospicules are considered as potential candidates for transporting material and kinetic energy to the corona (Woltjer 1954; Rush & Roberts 1954; Li & Ding 2009). There has been a great interest in spicular jets as a possible source of chromospheric heating and an important component of the chromosphere. If only a small fraction of the mass flux carried by spicules to the corona is able to escape, it may be sufficient to sustain the solar wind (Thomas & Athay 1961). In the initial $H\alpha$ observations, spicules were clearly seen to be performing an oscillatory motion in the vertical direction (see the review on spicule oscillations by Zaqarashvili & Erdélyi 2009). So far, models based on these drivers have not been able to quantitatively match both the heights and abundance of the observed solar spicules. There are several mechanisms that are invoked as drivers, for example, rebound shocks (Hollweg 1982), Alfvén pulses and waves (Liu et al. 2019; Scalisi et al. 2021; Oxley et al. 2020), solar global (p-mode) oscillations (De Pontieu et al. 2004), magnetic reconnection (Sterling & Mariska 1991; Shibata et al. 2007; Samanta et al. 2019), magnetic tension release (Martínez-Sykora et al. 2017) and the Lorentz force (Lijima & Yokoyama 2017) to name a few, to produce jets whose heights agree better with observations.

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Recently, Dey et al. (2022) have argued that solar convection below the photosphere can drive a forest of spicules with a distribution of heights between 5-25 Mm. Convection in the presence of magnetic fields, also known as magneto-convection (Haerendel 1992; Liu et al. 2019) leads to undulations in the photospheric layer of the Sun, which in turn propels the lighter plasma of the chromosphere upwards. Now, these perturbations cause various structures to form, such as dynamic fibrils, mottles, and spicules (Hansteen et al. 2006) or even macrospicules. There has been some observational evidence that dynamic fibrils found in and near active regions could be shorter in height than mottles found in the Quiet sun region or spicules that are coronal hole counterparts of the same jets (Shibata & Suematsu 1982; De Pontieu et al. 2004). More recent works like Zhang et al. (2012) and Narang et al. (2016) analysed Hinode and IRIS data, respectively, and proposed that Coronal Hole jets appear to be faster and longer than those in the Quiet Sun, even though their generation mechanism appears to be the same by the intensity of bright points at their bases. For macrospicules, a statistical study carried out for their properties using SDO/AIA observations detected in Active Regions, coronal holes and Quiet Sun, has shown their modulation as function of the overall magnetic field (see e.g. Kiss et al. 2017). They explored macrospicular properties (e.g., height, length, average speed, and width) and their dependencies on overall magnetic fields manifested by coronal holes and quiet solar regions, in the first half of Solar Cycle 24. Instead of macospicule types, they found long-term oscillatory behaviour in some properties.

Here, we perform a statistical study of solar spicules simulated by solving the radiative MHD (rMHD) equations using the Pencil Code¹ by varying the imposed magnetic field in the domain to gain insight on whether the ambient magnetic field modulates the height of these chromospheric jets.

This article is divided as follows: under section 2 we discuss the methodology we have adopted, under section 3, we discuss our findings from our analysis and conclude with further discussions in section 4.

2. METHODOLOGY

2.1. Radiative MHD simulations of the solar atmosphere

Here, we solve the equations of fully compressible magneto-hydrodynamics (MHD) for a 2-dimensional domain representing the solar subsurface convection, photosphere and the lower solar atmosphere above. The horizontal extent of the domain is 18 Mm and the total vertical extent including 5 Mm of convection zone is 37 Mm. We use a uniform grid size of 16 km in each direction. While the model has been described extensively in Chatterjee (2020) and Dey et al. (2022), we provide the framework used for completeness. Starting from the mass conservation equation,

$$\frac{\mathrm{D}\ln\rho}{\mathrm{D}t} = -\nabla \cdot \boldsymbol{u},\tag{1}$$

where, ρ is the local plasma density in units of the photospheric density, $\rho_0 = 2.7 \times 10^{-7} \text{ g cm}^{-3}$. The Navier-Stokes equation for the magnetized and compressible fluid velocity, \boldsymbol{u} , is

$$\frac{\mathrm{D}\boldsymbol{u}}{\mathrm{D}t} = -\frac{\nabla p}{\rho} + g_z \hat{\boldsymbol{z}} + \frac{\boldsymbol{j} \times \boldsymbol{B}}{\rho} + \mathbf{F}_L^{\mathrm{corr}} + \rho^{-1} \mathbf{F}_{\mathrm{visc}}, \qquad (2)$$

where j is the current density, B is the magnetic field, $\mathbf{F}_{L}^{\text{corr}}$ is the semi-relativistic correctiond to the Lorentz force due to Boris (1970) that has been discussed in detail in Chatterjee (2020). The viscous force is modelled as

$$\rho^{-1}\mathbf{F}_{\text{visc}} = \nu \left(\nabla^{2} \boldsymbol{u} + \frac{1}{3} \nabla \boldsymbol{\nabla \cdot u} + 2\mathbf{S} \cdot \nabla \ln \rho \right) + \zeta_{\text{shock}} \left[\nabla \left(\boldsymbol{\nabla \cdot u} \right) + \left(\nabla \ln \rho + \nabla \ln \zeta_{\text{shock}} \right) \boldsymbol{\nabla \cdot u} \right],$$
(3)

where, ν is the kinematic viscosity, and **S** is the traceless rate-of-strain tensor. We also use an enhanced viscous force at the shock fronts. We use an equation of state that includes ionization calculated assuming *local thermal equilibrium* (LTE). The pressure, p, is given by

$$p = \frac{\rho R_g T}{\mu(T)},$$

where, $R_q = k_B/m_u$ is the ideal gas constant, T, is the temperature and μ , is the effective mass given by

$$\mu = \frac{4x_{\rm He} + 1}{y_{\rm H}(T) + x_{\rm He} + 1} \,.$$

¹ https://pencil-code.org/

We consider the number fraction of Helium, x_{He} , to have a constant value of 0.089, whereas the fraction of ionized Hydrogen, denoted by y_{H} is a function of temperature. To calculate $y_{\text{H}}(T)$ at each time step Saha's ionization approximation is used. For further details, the reader is referred to Chatterjee (2020).

The induction equation is solved for the magnetic vector potential, \mathbf{A} , using the uncurled induction equation

$$\frac{\partial \mathbf{A}}{\partial t} = \mathbf{u} \times \mathbf{B} - \eta \mu_0 \mathbf{j} + \nabla \Psi. \tag{4}$$

In presence of an imposed vertical magnetic field, $B_{\rm imp}$, $\mathbf{B} = B_{\rm imp}\hat{\mathbf{z}} + \mathbf{B}'$ and $\nabla \times \mathbf{A} = \mathbf{B}'$ and η denotes molecular magnetic diffusivity. Gauge freedom allows us to set $\Psi = 0$ (Weyl gauge) at all times.

The initial stratification of temperature is obtained by collating the Model S (Christensen-Dalsgaard et al. 1996) for the interior and the atmospheric model by Vernazza et al. (1981). The initial density stratification corresponding to temperature is obtained by solving the hydrostatic balance subjected to the ionized ideal gas equation of state with ionization fraction given by the Saha-ionization model.

Finally, we have for the temperature equation, with turbulent diffusion, χ_t ,

$$\rho c_V T \frac{\mathrm{D} \ln T}{\mathrm{D} t} = -(\gamma - 1) \rho c_v T \nabla \cdot \boldsymbol{u} + \nabla \cdot (\mathbf{q}_{\mathrm{cond}} + \mathbf{q}_{\mathrm{rad}}) + \nabla \cdot (\rho T \chi_t \nabla \ln T) + \eta \mu_0 \boldsymbol{j}^2 + 2\rho \nu \mathsf{S}_{ij}^2 + \rho \zeta_{\mathrm{shock}} (\nabla \cdot \boldsymbol{u})^2 - \rho^2 \Lambda(T).$$
(5)

The Spitzer heat conduction flux is denoted \mathbf{q}_{cond} and described in Chatterjee (2020), j presents the current density and is associated with the Ohmic heating, S^2_{ij} denote the square of the tensorial components of the rate-of-strain tensor, S summed over all indices, i, j and, c_V is the specific heat capacity at constant volume. The radiative flux is denoted by \mathbf{q}_{rad} and is calculated using the method of long characteristics as described in Heinemann et al. (2006). To compute $\nabla \cdot \mathbf{q}_{\text{rad}}$, we solve the equation of radiative transport by adopting a grey atmosphere approximation, and by neglecting scattering contributions.

$$\hat{\mathbf{n}} \cdot \nabla I = -\kappa_{\text{tot}} \rho (I - S) \,, \tag{6}$$

where, $I(x, z, t, \hat{\vec{n}})$ is the specific intensity along direction $\hat{\vec{n}}$. The source function, $S = (\sigma_{\rm SB}/\pi)T^4$ is the frequency integrated Planck's function with $\sigma_{\rm SB}$ being the Stefan-Boltzman constant. The integration of Eq. (6) over solid angle, Ω , will give us $\nabla \cdot \mathbf{q}_{\rm rad}$ by

$$\nabla \cdot \mathbf{q}_{\text{rad}} = \kappa_{\text{tot}} \rho \oint_{4\pi} (I - S) \, \mathrm{d}\Omega.$$
 (7)

For this angular integration we use eight rays, four along x and z axes and along face diagonals of the x-z grid, and correctly scale the angular weight factors for two dimensions (Barekat & Brandenburg 2014). We do not use tabulated opacities, rather apply analytical power-law fits to the Rosseland mean opacity functions. We use solar abundances X=0.7381, Y=0.2485, metallicity Z=0.0134. The bound-free, free-free and H⁻ opacities are combined to give the total opacity, κ_{tot} . For the optically thin plasma above, we use a cooling function, $Q_{\text{thin}} = y_{\text{H}} n_{\text{H}}^2 \Lambda(T)$, where y_{H} is the ionization fraction of Hydrogen, and n_{H} is the number density of the element Hydrogen. $\Lambda(T)$ is a function of temperature in units of J m³s⁻¹ and available in tabulated form, computed from atomic data Cook et al. (1989). The radiation that escapes outward contributes to the cooling of the solar plasma. At the same time, an equal part of the optically thin radiative flux is emitted radially inward and is absorbed in the chromosphere, where it contributes to radiative heating instead of cooling (Carlsson & Leenaarts 2012). To calculate this heating at every time-step in a 3-dimensional simulation is non-trivial, therefore we approximate $Q_{\text{thin}} \to 0$ smoothly for $T < 30,000\,\text{K}$. Further, in absence of any self-sustained heating process, the temperature at the top boundary at $z = 32\,\text{Mm}$ is maintained at $10^6\,\text{K}$ to prevent the atmosphere from collapsing while the solar convection is building up. The saturation of convection takes about 1 hr of solar time. The results utilized in this work correspond to 25 min of data taken after the saturation of convection.

2.2. Spicule counting

In order to count the synthetic spicules as seen in emission, we first carry out forward modeling on the 2D simulation data in the [x, z] plane using a simple Gaussian expression. The synthetic intensity for an upper chromospheric or transition region line may be given by,

$$I_{\lambda} = \int G_{\lambda}(\rho, T)\varphi(T)dT. \tag{8}$$

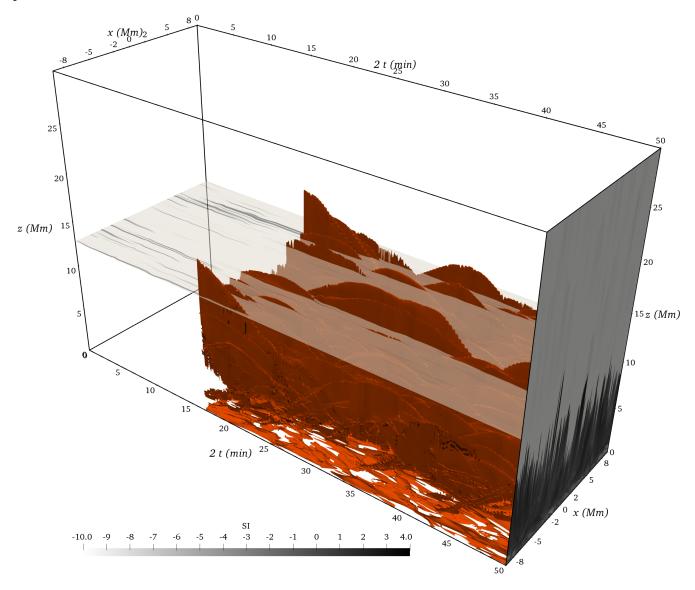


Figure 1. Spicules denoted by the iso-contour (red) of $15,000\,\mathrm{K}$ synthetic emission (SI) in the simulation domain with a resolution of $16\,\mathrm{km}$ for $25\,\mathrm{min}$ of solar time. Note that the time axis is stretched by a factor of 2. The tips of the spicule iso-contours clearly trace parabolic curves in the space-time cube. The horizontal plane at $z=13\,\mathrm{Mm}$, shaded by synthetic intensity contours for emission at $15,000\,\mathrm{K}$, denotes the x-t cross-section where each wiggle is a spicule during the time the spicule cross-section intersects the plane. The vertical x-z plane shows a snapshot of the forest of spicules at $t=25\,\mathrm{min}$ after the relaxation of the simulation. The imposed vertical magnetic field B_{imp} is $100\,\mathrm{G}$.

This expression is valid for temperatures between 10⁴–10⁸ K (see Landi & Chiuderi Drago 2008), where

$$G_{\lambda}(\rho, T) = \exp\left[-\left(\log(T/T_{\lambda})/w\right)^{2}\right]$$

is the "contribution" function for the line with $T_{\lambda}=15000\,\mathrm{K}$ and $w=\log 1.8$ and $\varphi(T)=(\rho/\overline{\rho})^2ds/dT$ is the differential emission measure scaled with the square of the horizontally averaged density, $\overline{\rho}(z)$. Similar expressions have been used by Iijima & Yokoyama (2017) for depicting synthetic coronal and chromospheric jets, respectively. Normally, the integration is performed along the line-of-sight (LOS), the infinitesimal element along which is ds. However, for two-dimensional models, the integration is irrelevant as there is only one grid point along the LOS. Counting of solar spicules is carried out by creating a time-distance data cube from the time evolution of the 2D simulation in [x,z]-plane. At a given height, z, we take a horizontal cross-section (see Fig. 1) i.e., parallel to the [x,t] plane and plot the emission contours above a predefined threshold. This procedure yields 2D shaded contour plots featuring distinct

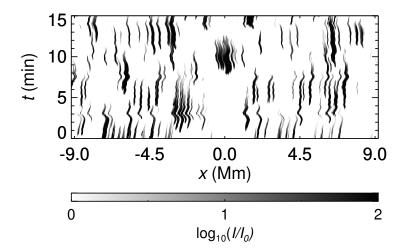


Figure 2. The horizontal plane at $z = 10 \,\mathrm{Mm}$ for the 100 G simulation setup as in Fig. 1, where the colorbar is for the synthetic intensity. The wiggle-like structures in black color depict the cross-section of the spicules. Note that from here, it can be seen that no spicule lies fully in a single vertical slice, i.e., a z - t slice.

wiggle-like structures, which correspond to x-t cross-sections of the simulated spicules as shown in Fig. 2. At any height z, we can then just count the number of distinct wiggle-like features by prompting a threshold brightness of pixels that represent the number of spicules whose height $\geq z$. Essentially, we construct a cumulative distribution function versus a height plot. We take note of this count every equidistant interval of the height. This methodology is repeated for all the simulations with varying imposed vertical magnetic field strengths, i.e., $B_{\rm imp} = 10~{\rm G}, 50~{\rm G}, 100, 200~{\rm G}$.

2.3. Parabola fits

After the spicule counting exercise, we shift our attention to kinematics of spicules by studying their trajectories in [z-t] plane that closely resemble parabolas. These trajectories can be used to estimate the deceleration of the spicule tips. In order to obtain a best-fit parabola for a given spicule trajectory in height-time, we once again use the 3D data cubes in x-z-t space. Because of the kink mode or swaying of the spicule, the trajectory of the tip does not lie in a single [z,t] plane with fixed x, but occupies neighboring planes too. Therefore, we visually identify the x and z coordinates of interest; Subsequently, we generate [z,t] cross-sections at these specified x coordinates. To obtain the final images, we employ the Maximum Intensity Projection (MIP) technique (Sakas et al. 1995).

The MIP technique is widely used for deep learning studies for Magnetic Resonance Angiogram (MRA) images (Sun & Parker 1999) - a type of MRI applied explicitly to blood vessels. Here, MIP operates by taking a central slice as input and considering 2 or 3 adjacent slices on both sides of the chosen x coordinate. Then, it calculates a resultant slice by projecting the pixel with the highest brightness value from each of the input [z,t] planes onto it. This process ultimately yields a 2D projection of a 3D object. The rationale behind adopting the MIP technique lies in the oscillatory mode of spicules, analogous to human blood vessels. Due to their swaying motion, several spicules span across multiple adjacent z-t planes, rather than being confined to a single slice with given x. Consequently, constructing a vertical cross-section at a specific index may not accurately capture the complete shape of the target spicule. The utilization of MIP enhances the comprehensive representation of intricate 3D structures. However, the implementation technique employed by MIP, which generates an overlapped image of cumulative slices, presents challenges in studying shorter spicules. The heightened density of short spicules complicates their analysis. Consequently, to facilitate a more manageable investigation, we have chosen to narrow our focus to spicules surpassing a predefined minimum height criterion. Specifically, our analysis concentrates on spicules lying above the 75th percentile of maximum height. This approach is supported by Suematsu et al. (1995), who argued that studying longer spicules yields more reliable results, as shorter ones can frequently be mistaken for fibrils and other prevalent structures.

Subsequently, we employ a second-order polynomial, representing a perfect parabolic equation, for fitting purposes. The selection of relatively longer spicules for this fitting is motivated by the observation that the parabolic nature is

obscured primarily due to the overlap of spicules at lower heights. The fitted parabola adopts a general equation as

$$z = -at^2 + bt + c.$$

where $a, b \ge 0$ will correspond to the acceleration and initial velocity, respectively. For the final step, we visually select seven data points defining the parabola, which the fitting routine uses to determine the best-fit curve. It is worth noting that both visual error and fitting-related error decrease as more data points are incorporated into the fitting process, as expected. However, for practical efficiency, we limit our analysis to a 7-point fit. While efforts have been made to minimize errors, it is crucial to acknowledge that errors persist due to visual inaccuracy, and these errors become more pronounced while fitting shorter spicules that often overlap with each other. 2

3. RESULTS

We use two different methods to visualize our spicule height distribution results. Fig. 3a provides an overview of the overall behavior. This is achieved by normalizing both the height and number of spicules. This normalization process followed is given by Eqs. (9)-(10). It is worth noting that our method yields the count of spicules longer than a given height where the horizontal cross-sections are taken. However, our definition of the CDF(h) refers to the number of spicules shorter than a given height, h. Height is normalised using the formula:

$$h_{\text{norm}} = \frac{h - h_{\text{min}}}{h_{\text{max}} - h_{\text{min}}} \tag{9}$$

The minimum height has been chosen differently for each imposed vertical magnetic field, $B_{\rm imp}$, due to the fact that it is difficult to discern the shortest spicules using our method. Incorporating the cumulative distribution function (CDF) plots, we established minimum heights for analysis, selecting values of 10 Mm, 8 Mm, 5.6 Mm, and 4.45 Mm corresponding to magnetic field strengths of 10G, 50G, 100G, and 200G, respectively. Implying that the minimum height after which a spicule can be distinctly identified, decreases with increasing magnetic field strength as it can be seen in Fig. 1. These heights signify the point beyond which there is a consistent and monotonic decrease in the spicule count. The non-monotonic behavior observed below these chosen heights may be attributed to challenges in distinctly identifying spicule structures at lower altitudes. The number of spicules longer than a given height, h, is normalized using the following:

$$N_{\text{norm}} = \frac{N_{\text{total}} - N(h)}{N_{\text{total}}},\tag{10}$$

where, N_{total} , is the total number of unique spicules observed during the duration of 30 min in any simulation. This plot illustrates that, irrespective of the magnetic field strength present in the chromosphere, the trend of normalized height versus normalized frequency remains largely consistent. This uniformity underscores the common characteristics exhibited by a distribution of solar spicules.

In panels (b) and (c) of Fig. 3, only the CDF on the vertical axis is normalized while keeping the original values of heights in megameters on the horizontal axis. By repeating the above procedure for all the data sets for each $B_{\rm imp}$, we obtain the CDF versus height for each case. These plots reveals that the maximum height attained by simulated spicules decreases, and the curve flattens earlier with increasing magnetic field strength. This signifies an inverse relation between the maximum height reached by spicules and the magnetic field strength in the domain. Let us explore the possible reasons for this anti-correlation. One possibility is the suppression of the intensity of solar convection in the presence of stronger magnetic fields. The other reason could be the dependence of the coronal pressure on the magnetic field. The higher the coronal pressure, the more challenging will it be for solar spicules to reach higher altitudes in the solar atmosphere. To test the first hypothesis, we look at the warping of the optical depth, $\tau = 0.1$ surface over the domain and for 25 min of simulation data. The amplitude of distortion of the $\tau = 0.1$ line is shown in Figs. 4a–d for the imposed magnetic field values indicated.

We summarize our findings in Fig. 5a, where we first note a decrease of the warping amplitude with increasing $B_{\rm imp}$ (for lower values of $B_{\rm imp}$) and thereafter a levelling. This result only partially explains the slight decrease of maximum spicule height when the imposed magnetic field increases by a factor of 20. Next, we plot the coronal gas pressure averaged between heights 8–14 Mm for all four cases. With increasing $B_{\rm imp}$, we find that, in fact, gas pressure decreases

² Python codes for the Spicule analysis are available at github.com/Kartav33/Spicules_Analysis_Codes

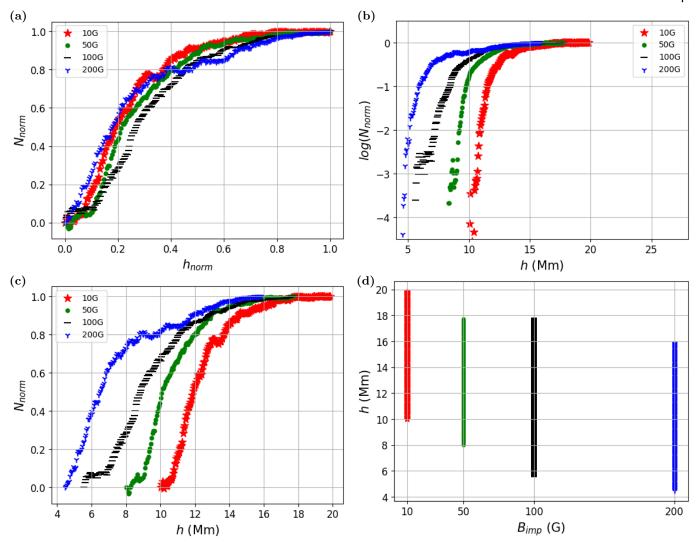


Figure 3. (a) The normalized cumulative distributive function of spicule count N_{norm} versus normalized height. (b) N_{norm} in logarithmic scale versus height in its original values. (c) Same as the top right panel, key difference being the N_{norm} in normal scale. (d) Height of all the spicules that were studied plotted against the magnetic field imposed for each of the four numerical experiments indicated in the legend.

slightly while the total pressure, $p_g + p_g/\beta$, varies as $B_{\rm imp}^2$ as expected for low plasma- β regimes (see Figs. 5b–c). That may be the reason why we see only a slight decrease in the maximum spicule heights upon increasing the magnetic field. It is also worth mentioning that even though the magnetic pressure is enhanced 400 times from $B_{\rm imp} = 10\,{\rm G}$ to 200 G (Fig. 5b), the decrease in spicule heights is not as spectacular. This is the case probably because the coronal gas pressure actually decreases slightly upon increasing $B_{\rm imp}$ as shown in panel (c) of the same figure. This indicates that in simulations like those used here, the magnetic pressure is not playing a significant role in determining the strength of the slow mode shocks that accelerate the spicule plasma (Dey et al. 2022), and in turn, govern the maximum height attained by the spicule tips.

Next, we present results from our study of the parabolic nature of spicules tips in z-t space (see Fig. 6). Here, the parabolic nature is clearly discernible only in the top ~ 25 percentile of the height distribution. Therefore, a total of 8 spicules were isolated for each of the four cases. For every spicule, we fitted the parabola three times by selecting points manually on the time-distance curve every time and averaged the fitting parameters in order to obtain an average value. In order to compare the deceleration, g_d , for the different cases of imposed magnetic fields, we normalized the values by a constant solar gravity of $g_{\odot} = 274 \text{ m s}^{-2}$. We refer to the Table. 1 for the first few entries for each case. From Fig. 7, a monotonic decline can be seen in the values of deceleration of spicules with increasing imposed magnetic

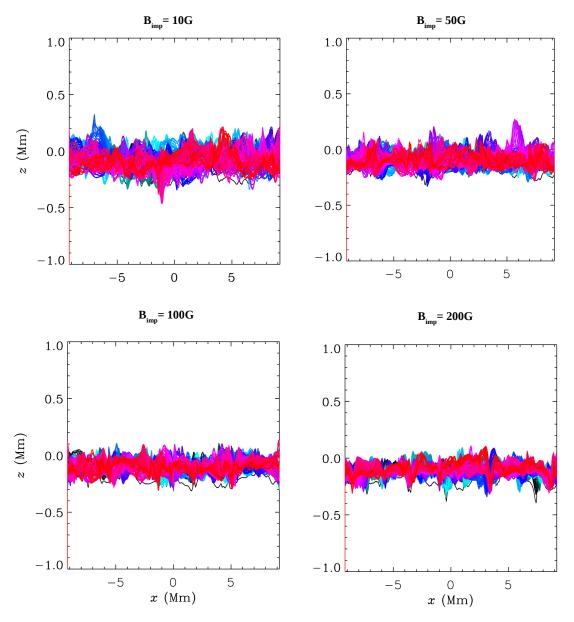


Figure 4. The oscillation of the $\tau = 0.1$ surface for data spanning a duration of 25 min for four different cases of magnetic field. The color of the curve corresponds to its time stamp.

field. It is worth mentioning that for the weaker magnetic field strength, the deceleration of the longer spicules is much higher than the local solar gravity. The deceleration becomes comparable to g_{\odot} for the fields lying between 50-100 G and finally much lower than g_{\odot} under strong magnetic field strengths.

4. DISCUSSION

Our 2D rMHD simulations indicate that the strength of the local magnetic field plays a direct role in determining the maximum height of the solar spicules. We identify one possible reasons, namely, the suppression of convection at the photosphere. Moreover, if convection is suppressed, then the "breathing" of the granules in the upper photosphere also decreases, and so does the quasi-periodic kicks to the lighter plasma above in order to form spicular structures. Likewise, a higher ambient coronal pressure may also suppress the growth in the height of the spicules, by affecting the strength of the propagating slow mode MHD shocks. Note that in our simulations, the coronal temperature is fixed at 10^6 K and does not vary in tandem with the imposed magnetic field. The atmosphere above the active region is known

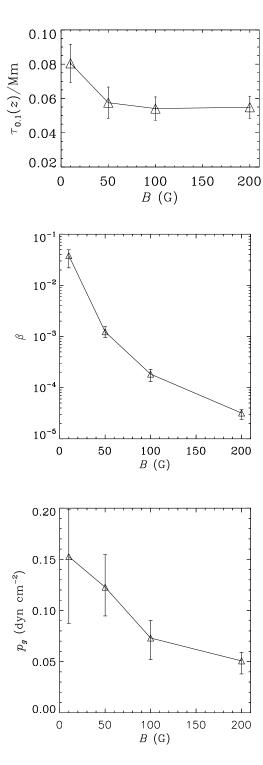


Figure 5. (a) Root-mean-square of the vertical oscillation extent of the $\tau=0.1$ surface averaged over all grid points in the horizontal direction and over 25 min of data, plotted for the four imposed vertical magnetic field cases shown in Fig. 4. (b) Plasma- β and (c) gas pressure in the atmosphere between 8–14 Mm for different values of $B_{\rm imp}$. The error bars denote the spread over 15 min of data.

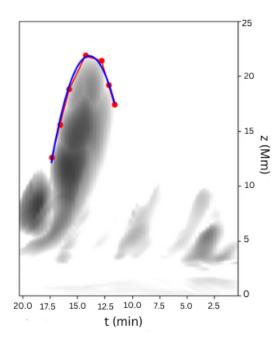


Figure 6. Figure shows the fitted parabola with blue line (smooth line), visually selected points by red dots and the red dotted line, where the equation of the parabola fitted is $z = -0.81t^2 + 22.49t - 134.45$, where t is in min and z in Mm. This is done for the same test case data from Dey et al. (2022) where B_{imp} is 200 G. This spicule belongs to the subset that was made under the same criteria as we have used here.

B_{imp}	z (Mm)	$g_d \; (\mathrm{m s}^{-2})$	$ g_d/g_{\odot} $
10G	19.6	645.22	2.35
	18.8	422.73	1.54
50G	17.7	311.48	1.14
	17.3	511.93	1.87
100G	17.7	102.34	0.37
	17.4	93.44	0.34
200G	15.8	66.75	0.24
	15.1	17.80	0.06

Table 1. Deceleration, g_d , calculated using the leading coefficient of the fitted parabola for every first and second longest spicules in each case.

to be much hotter than in Quiet Sun regions, which in turn is hotter than Coronal Hole regions. However, in 2D models like those used here, there is no self consistent coronal heating. It remains to be verified if artificially increasing the temperature at the coronal boundary in proportion to the $B_{\rm imp}$ causes a further decrease in the spicule heights in our numerical experiments than those depicted in Fig. 3d. On the other hand, explaining our result regarding the decrease of the deceleration of the spicules with increasing magnetic field is both non-trivial and counter-intuitive and may have to do with how magnetic tension affects the parabolic shape of the time-distance curve of the spicule tips.

The MIP technique implemented in this work produces an overlapped image of trajectories of neighboring spicules as well, as previously mentioned, due to which a restricted analysis was carried out by only considering spicules longer than 75 percentile in height distribution. In the future, one can make an improved and modified extension of MIP to study even the shorter spicules that flags off all the neighboring overlapping spicule trajectories that are not of any interest and thus allow us to study the shorter spicules as well. Furthermore, an improvement can be made while analysing the deceleration of the simulated spicules. Instead of fitting a two-dimensional parabola to a (2+1)-

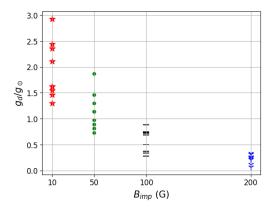


Figure 7. Plot showing the normalized deceleration versus the imposed magnetic field for 8 tallest spicules for each B_{imp} .

dimensional spicule of Fig. 1 that has been collapsed on a single plane using MIP, one can go over fitting a series of 2-dimensional parabola to the actual (2+1)D spicules in the domain, ultimately fitting a curved surface and allowing a topographic study. This will not only provide the deceleration data with much higher accuracy but will also open the possibility of doing a study involving the spicule velocity and its non-parabolic nature.

The next step should be to compare our theoretical findings with observed spicules near the solar limb by classifying them according to the strength of the underlying photospheric magnetic field strength. A systematic study can be carried out by combining several near simultaneous data sets from both the Broadband Filter Imager (BFI) for chromospheric images and Narrowband Filter Imager (NFI) for photospheric magnetograms onboard the Hinode spacecraft.

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